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## Lecture 4: Tensors III: overcomplete tensor decomposition via smoothed analysis

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## 1 Introduction

In last lecture, we showed that Jennrich's algorithm is not very noise-robust. Furthermore, for a tensor $T=\sum_{i=1}^{k} u_{i}^{\otimes 3}, u_{i} \in \mathbb{R}^{d \times d \times d}$, Jennrich's requires the assumption that the $u_{i}$ vectors are linearly independent. This means that $k \leq d$. However, in the last lecture, we saw examples in which $k>d$ (called the "overcomplete setting") but Jennrich's still succeeds, to an extent (when $k$ is very large it eventually fails). Theoretically speaking, Jennrich's algorithm cannot handle cases in which $k>d$.

This lecture examines the case in which $k \gg d$ by using higher-order tensors.

## 2 Example

This example will illustrate that looking at higher-order tensors can allow to access higher-order tensors.

Consider $q=\sum_{i=1}^{k} \lambda_{i} \mathcal{N}\left(\mu_{i}, I\right)$, where $I$ is the identity matrix and $\mathcal{N}$ refers to the normal distribution. If $x \sim q$ then the following holds (refer to Lecture 2 for details):

$$
\mathbb{E}\left[x^{\otimes 3}\right]=\sum_{i=1}^{k} \lambda_{i} \mu_{i}^{\otimes 3}+\left(\sum_{i=1}^{k} \lambda_{i} \mu_{i}\right) \otimes_{3} I
$$

Here, we can recover $\mu_{i}$ for all $i$ as long as they are all linearly independent via Jennrich's algorithm.

Suppose we instead consider $\mathbb{E}\left[x^{\otimes 4}\right]$ :

$$
\begin{aligned}
\mathbb{E}\left[x^{\otimes 4}\right] & =\sum_{i=1}^{k} \lambda_{i} \mathbb{E}\left[\left(\mu_{i}+g\right)^{4}\right] \quad(g \text { drawn according to } \mathcal{N}(0, I)) \\
& =\sum_{i=1}^{k} \lambda_{i} \mu_{i}^{\otimes 4}+\sum_{i=1}^{k} \lambda_{i} \mu_{i}^{\otimes 2} \otimes_{4} I+\sum_{i=1}^{k} \lambda_{i} \mathbb{E}\left[g^{\otimes 4}\right]
\end{aligned}
$$

Now, instead of having a third order tensor as the first term, we have a fourth order tensor. Suppose we have $T=\sum_{i=1}^{k} u_{i} \otimes u_{i} \otimes u_{i} \otimes u_{i} \otimes u_{i}$. Recall the function vec: $\mathbb{R}^{d \times d} \rightarrow \mathbb{R}^{d^{2}}$ which takes in a matrix and turns it into a vector. Then we may define $T^{\prime}$ as follows: $T^{\prime}=\sum_{i=1}^{k} \lambda_{i} \operatorname{vec}\left(u_{i} \otimes u_{i}\right) \otimes \operatorname{vec}\left(u_{i} \otimes u_{i}\right) \otimes u_{i}$.
$T^{\prime}$ is a third-order tensor, and one can apply Jennrich's to recover the tensor decomposition as long as it holds that $\left\{\operatorname{vec}\left(u_{i} \otimes u_{i}\right)\right\}_{i=1}^{k}$ is a linearly independent set. From Lecture 2, we know that this is implied if $\left\{u_{i}\right\}_{i=1}^{k}$ is a linearly independent set. However, we explore whether Jennrich's can be applied to $T^{\prime}$ even if the set $\left\{u_{i}\right\}_{i=1}^{k}$ is not linearly independent, $\operatorname{since}\left\{\operatorname{vec}\left(u_{i} \otimes u_{i}\right)\right\}_{i=1}^{k}$ is a set of dimension $d^{2}$ dimension.

To summarize this example: We explore whether one can alter the decomposition of a tensor $T$ which is higher-order, using the vec function. We hope that even if the $u_{i}$ are not linearly independent, using the vec function will create a linearly independent set, meaning that we could use Jennrich's when $k$ is on the order $d^{2}$.

### 2.1 Counterexample

This counter example shows that we cannot go past $k>O(d)$. Suppose $k=2 d$, and let $\left\{a_{i}\right\}_{i=1}^{d},\left\{b_{i}\right\}_{i=1}^{d}$ be two orthonormal basis in $\mathbb{R}^{d}$. Then consider the set of vectors $\left\{u_{i}\right\}_{i=1}^{2 d}=\left\{a_{1}, \ldots, a_{d}, b_{1}, \ldots, b_{d}\right\}$. Clearly this is a linearly dependent set of vectors. Furthermore, we make the following claim:

Claim 1. The set $V=\left\{\operatorname{vec}\left(u_{i} \otimes u_{i}\right)\right\}_{i=1}^{2 d}$ are linearly dependent.
Proof. Because $\left\{a_{i}\right\}_{i=1}^{d}$ is an orthonormal basis, we know that

$$
\sum_{i=1}^{d} a_{i} a_{i}^{\top}=\sum_{i=1}^{d} a_{i} \otimes a_{i}=I
$$

Furthermore, the same holds for orthonormal basis $\left\{b_{i}\right\}_{i=1}^{d}$ :

$$
\sum_{i=1}^{d} b_{i} \otimes b_{i}=I
$$

This shows that

$$
\begin{aligned}
\sum_{i=1}^{d} a_{i} \otimes a_{i}=\sum_{i=1}^{d} b_{i} \otimes b_{i} & \Longrightarrow \sum_{i=1}^{d} \operatorname{vec}\left(a_{i} \otimes a_{i}\right)=\sum_{i=1}^{d} \operatorname{vec}\left(b_{i} \otimes b_{i}\right) \\
& \Longrightarrow \exists S \subset[2 d], \exists T \subset[2 d], S \cap T=\emptyset \text { s. t. } \sum_{i \in S} V_{i}=\sum_{i \in T} V_{i}
\end{aligned}
$$



Figure 1: This figure attempts to illustrate the "landscape of difficulty" of a problem over problem instances. The $x, y$ planes simplify the notion of different parameters of the underlying problem instance, and the $z$ axis represents "hardness".

This proves that the set $V$ is in fact linearly dependent. As such, this is a valid counter example proving that by reshaping using the vec function, we do not obtain the desired hope that one could obtain linear independence and apply Jennrich's algorithm.

One should note that in reality, it is not likely that our components are delicately chosen such that they are the union of two orthonormal basis. In the context of Figure 1, this counterexample could be viewed as one of the peaks.

## 3 Beyond Worst-Case Analysis

We introduce the concept of "average case analysis." An early description of this comes from [Lev86]: "Many interesting combinatorial problems were found to be NP-complete. Since there is little hope to solve them fast in the worst case, researchers look for algorithms which are fast just 'on average'. This matter is sensitive to the choice of a particular NP-complete problem and a probability distribution of its instances."

This represents Perspective 1: For any given random problem instance, the probability of it being hard is small.

Smoothed analysis is a development on top of average case analysis, and was introduced by [ST03], introduced to analyze typical examples we encounter in reality. This represents Perspective 2: For an arbitrary problem instance, if we add to it a small amount of noise, the probability that the noised instance is still hard is small.

## 4 Smoothed Analysis of Tensor Decomposition

Our model is as follows: $\rho>0$ is the smoothing parameter and dictates how much noise we add to each sample, $k$ is the number of components, and $l$ is the order of the tensor.

Then we receive the problem instance as follows:

1. Nature picks arbitrary vectors $\left\{u_{i, j}^{\prime}\right\}$ for $i \in[k], j \in[l]$.
2. Nature samples $u_{i, j}=u_{i, j}^{\prime}+\frac{\rho}{\sqrt{d}} \cdot g_{i, j}$ where $g_{i, j} \sim \mathcal{N}(0, I)$.
3. We observe $T=\sum_{i=1}^{k} u_{i, 1} \otimes \cdots \otimes u_{i, l}$.

Theorem 1. With prob $1-1 /$ superpoly $(d)$ over the randomness of $\left\{g_{i, j}\right\}$ we can recover the $u_{i, j}$ for all $i, j$ given $T$, if $k \leq 0.99 d^{\lfloor(l-1) / 2\rfloor}$ [BCMV13].

Going back to the example, suppose we have some tensor $T^{\prime}=\sum_{i} \operatorname{vec}\left(u_{i} \otimes v_{i}\right) \otimes$ $\left.\left(w_{i} \otimes x_{i}\right) \otimes y_{i}\right)$, we would like to show that $\left\{\operatorname{vec}\left(u_{i} \otimes v_{i}\right)\right\}_{i=1}^{k}$ is robustly linearly independent (due to addition of noise) as well as $\left\{\operatorname{vec}\left(w_{i} \otimes x_{i}\right)\right\}_{i=1}^{k}$.

Definition 1. (Khatri-Rao Product) The Khatri-Rao product of $U$ and $V$ is: $U \star V=$ $\left(\operatorname{vec}\left(u_{1} \otimes v_{1}\right) \cdots \operatorname{vec}\left(u_{k} \otimes v_{k}\right)\right)$ where each entry is a column.

Thus we would like to show that $U \star V$ is robustly full-rank, in the sense that its minimum value is not too small. Specifically, the following theorem is useful:

Theorem 2. In the smoothed analysis setting, with probability at least $1-k \exp (-\Omega(d))$ : $\sigma_{\text {min }}(U \star V) \geq \operatorname{poly}(\rho, 1 / \sqrt{d})$. BCMV13, ADM $\left.{ }^{+} 18\right]$

Proof. Begin with $U, V \in \mathbb{R}^{d \times k}$, which are the worst case matrices. Then the smoothed matrices are:

$$
\begin{aligned}
& \tilde{U}=U+\frac{\rho}{\sqrt{d}} \mathcal{N}(0, I)^{d \otimes k} \\
& \tilde{V}=V+\frac{\rho}{\sqrt{d}} \mathcal{N}(0, I)^{d \otimes k}
\end{aligned}
$$

The statement that we prove is that $\sigma_{\min }(\tilde{U} \star \tilde{V}) \geq \operatorname{poly}\left(\rho^{2} / d^{3}\right)$ with high probability. Note that Theorem 2 refers to $U, V$ as worst-case matrices.

We first employ a reduction for minimum singular value to leave-one-out distance:

Definition 2. (Leave-one-out distance) For $M \in \mathbb{R}^{n \times k}$, the leave-one-out distance of $M$, denoted $l(M)$, is defined as $l(M)=\min _{i \in[k]}\left\|\Pi_{i} M_{i}\right\|_{2} . \Pi_{i} \frac{1}{i}$ s the projector to the orthogonal complement of $\operatorname{span}\left(M_{1}, \ldots, M_{i-1}, M_{i+1}, \ldots, M_{k}\right)$.

Lemma 1. $\sigma_{\min }(M) \geq \frac{1}{\sqrt{k}} l(M)$.
Proof. Take any $i \in[k]$. Without loss of generality, let $i=1$. Then the following holds:

$$
\begin{aligned}
l(M) & \leq\left\|\Pi \frac{1}{1} M_{1}\right\|_{2} & & \\
& =\min _{v \in \operatorname{span}\left(M_{2}, \ldots, M_{k}\right)}\left\|M_{1}-v\right\|_{2} & & \text { (by definition) } \\
& =\min _{\vec{\lambda}}\left\|M_{1}-\sum_{i>1} \lambda_{i} M_{i}\right\|_{2} & & \text { (re-writing explicitly) } \\
& \leq\left\|M_{1}+\sum_{i>1} \frac{u_{i}}{u_{1}} M_{i}\right\|_{2} & & \text { (Taking } \left.\lambda_{i}=-u_{i} / u_{1}\right) \\
& =\frac{1}{\left|u_{1}\right|}\left\|\sum_{i=1}^{k} u_{i} M_{i}\right\|_{2} & & \text { (by summing over all } i \text { ) } \\
& =\frac{1}{\left|u_{1}\right|}\|M u\|_{2} & & \text { (by taking } u \text { to be the minimum singular vector of } M \text { ) } \\
& =\frac{\|u\|_{2}}{\left|u_{1}\right|} \sigma_{\min }(M) & & \text { (property of minimum singular vector) }
\end{aligned}
$$

The largest entry in $u$ is always at least $\frac{1}{\sqrt{k}}\|u\|_{2}$. So in general, we can replace $u_{1}$ in the last line with the largest absolute entry in $u$ to obtain: $l(M) \leq \sqrt{k} \sigma_{\min }(M) \Longrightarrow$ $\frac{1}{\sqrt{k}} l(M) \leq \sigma_{\min }(M)$.

Since we have shown that the minimum singular value of a matrix is lowerbounded by a factor times $l(M)$, it suffices to show that $l(\tilde{U} \star \tilde{V})$ is not too small in order to show that $\sigma_{\min }(\tilde{U} \star \tilde{V})$ is not too small. In other words, it suffices to show that $\forall i \in[k],\left\|\Pi_{i}(\tilde{U} \star \tilde{V})_{i}\right\|_{2}$ is not too small.

Note that $\operatorname{dim}\left(\Pi \frac{1}{i}\right)=d^{2}-(k-1)$ in this setting because the matrix is in $d^{2}$ and there are $k-1$ columns which make the span. By assumption, $k \leq .99 d^{2}$. Hence $\operatorname{dim}\left(\Pi \frac{1}{i}\right) \geq .01 d^{2}=\Omega\left(d^{2}\right)$.

In order to remove some aspect of randomness, we focus on proving a stronger statement: Fix $W \subset \mathbb{R}^{d^{2}}$ such that $\operatorname{dim}(W) \geq .01 d^{2}$. Then $\left\|\Pi_{W}(\tilde{U} \star \tilde{V})_{i}\right\|_{2}$ is not too small for all $i \in[k]$, with high probability.

We begin with a toy example. Namely, we start with one vector instead of two: Let $W \subset \mathbb{R}^{d}, \operatorname{dim}(W) \geq .01 d$. If $\tilde{u} \in \mathbb{R}^{d}$ is given by $\tilde{u}=u+\frac{\rho}{\sqrt{k}} g(g \sim \mathcal{N}(0, I))$ then $\left\|\Pi_{W} \tilde{u}\right\|_{2}$ is not too small with high probability.

Proof. Let $D=\operatorname{dim}(W), D \geq .01 d$. Let $\left\{w_{1}, \ldots, w_{D}\right\}$ be an orthonormal basis for $W$. Then $\left\langle g, w_{1}\right\rangle, \ldots,\left\langle g, w_{D}\right\rangle$ are all independent random variables (by orthogonality of
basis).

$$
\begin{aligned}
\left\|\Pi_{W} \tilde{u}\right\|_{2} & =\left\|\left(\left\langle w_{1}, \tilde{u}\right\rangle \cdots\left\langle w_{D}, \tilde{u}\right\rangle\right)\right\|_{2} & & (W \text { is an orthonormal basis) } \\
& \geq \max _{j \in[D]}\left|\left\langle w_{j}, \tilde{u}\right\rangle\right| & & (\mathrm{L} 2 \text { norm is at least value of largest entry) }
\end{aligned}
$$

Every entry $\left\langle w_{i}, \tilde{u}\right\rangle$ can be written as $\left\langle w_{i}, u\right\rangle+\frac{\rho}{\sqrt{d}}\left\langle w_{i}, g\right\rangle$. Recall that all the $\left\langle w_{i}, g\right\rangle$ are independent Gaussian random variables, and because we are taking the dot product of a random Gaussian and a normal vector, the term $\frac{\rho}{\sqrt{d}}\left\langle w_{i}, g\right\rangle$ is in fact a random normal variable with mean 0 and variance $\frac{\rho^{2}}{d}$. Thus, all the dot products $\left\langle w_{1}, \tilde{u}\right\rangle, \ldots,\left\langle w_{D}, \tilde{u}\right\rangle$ are independent Gaussians with variance $\frac{\rho^{2}}{d}$, and they each have some arbitrary mean due to the arbitrary $u$.

Fact 1. (Gaussian anti-concentration). For $g \sim \mathcal{N}(0,1)$ and for any interval $I \subset \mathbb{R}$ of length $t, \operatorname{Pr}[g \in I] \leq \Omega(t)$.

The proof follows from that the probability of landing in interval $I$ is bounded above by some rectangle of width $t$ which contains the area under the curve of the probability density function. By anti-concentration, $\operatorname{Pr}\left[\left|\left\langle w_{j}, \tilde{u}\right\rangle\right| \leq t \frac{\rho}{\sqrt{d}}\right] \leq \Omega(t)$. This implies that $\operatorname{Pr}\left[\left|\left\langle w_{j}, \tilde{u}\right\rangle\right| \leq t \frac{\rho}{\sqrt{d}}, \forall j\right] \leq \exp (-\Omega(d))$. This shows that with high probability, $\left\|\Pi_{W} \tilde{u}\right\|_{2}$ is at $O\left(\frac{\rho}{\sqrt{d}}\right)$.

The above proof does not generalize to many vectors. Thus we show a proof that does generalize. We pick a row-echelon basis for $W$ of the form ( $\star$ indicates arbitrary value whose absolute value is upper-bounded by 1 ) and without loss of generality, because it exists up to permutation:

$$
\begin{aligned}
w_{1} & =(1, \star, \ldots, \star) \\
w_{2} & =(0,1, \star, \ldots, \star) \\
w_{3} & =(0,0,1, \star, \ldots, \star) \\
& \vdots
\end{aligned}
$$

We reveal $\left\langle w_{j}, \tilde{u}\right\rangle$ in reverse order $j=D, D-1, \ldots, 1$. That is, we look at $\left\langle w_{i}, \tilde{u}\right\rangle$ conditioned on $\left\langle w_{D}, \tilde{u}\right\rangle, \ldots,\left\langle w_{i+1}, \tilde{u}\right\rangle$.

$$
\begin{aligned}
\left\langle w_{i}, \tilde{u}\right\rangle & =\left\langle w_{i}, u\right\rangle+\frac{\rho}{\sqrt{d}}\left\langle w_{i}, g\right\rangle \\
& =\left\langle w_{i}, u\right\rangle+\frac{\rho}{\sqrt{d}}\left(g_{i}\left(w_{i}\right)_{i}+\sum_{j>i} g_{j}\left(w_{i}\right)_{j}\right)
\end{aligned}
$$

$w_{j}$ is arbitrary for $j>i$ so we can think of $\sum_{j>i} g_{j}\left(w_{i}\right)_{j}$ as arbitrary. Hence, $g_{i}\left(w_{i}\right)_{i}$ is still independent, even when conditioned on $\left\langle w_{i+1}, \tilde{u}\right\rangle, \ldots,\left\langle w_{D}, \tilde{u}\right\rangle$. Applying anti-concentration, we have that

$$
\operatorname{Pr}\left[\forall i,\left|\left\langle w_{i}, \tilde{u}\right\rangle\right| \leq O\left(\frac{\rho}{\sqrt{d}}\right)\right] \leq \exp (-\Omega(d))
$$

In general however, we care about the scenario in which there is $\left\|\Pi_{W} \tilde{u} \star \tilde{v}\right\|_{2}$ and $W$ is a subspace of dimension $d^{2}$. This will require a 2 dimensional row-echelon basis $\left(W^{(i, j)}\right) \subset \mathbb{R}^{d \times d}$. We construct $W^{i, j}$ to be a matrix in $\mathbb{R}^{d \times d}$ where

$$
\left(W^{i, j}\right)_{a, b}=\left\{\begin{array}{l}
0, \text { if } a<i \text { or } b<j \\
1, \text { if } a=i \text { and } b=j \\
*, \text { otherwise }
\end{array}\right.
$$

High level idea: we can look at the vectors $\left\{W^{i, j} \tilde{v}\right\}_{j}$. For every $i$, we can extract vector $v^{i}$ and look at $\left\langle v^{i}, \tilde{u}\right\rangle$. If the $v^{i}$ are not too different from row-echelon vectors, then we can show that this is not too small.

## References

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